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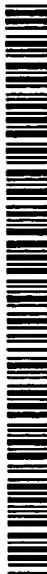
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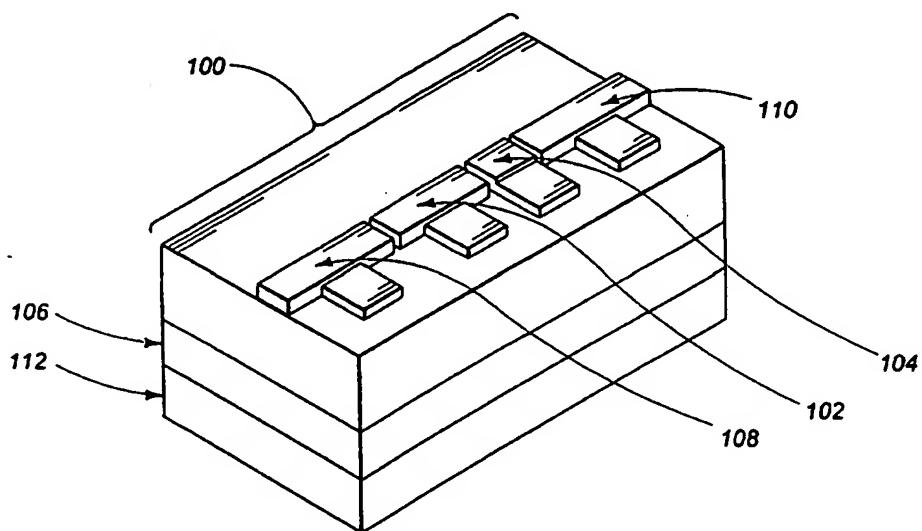
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(54) Title: IMPROVED MIRROR AND CAVITY DESIGNS FOR SAMPLED-GRATING DISTRIBUTED BRAGG REFLECTOR LASERS



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(57) Abstract: A tunable laser comprised of a gain section for creating a light beam by spontaneous emission over a bandwidth, a phase section for controlling the light beam around a center frequency of the bandwidth, a cavity for guiding and reflecting the light beam, a front mirror bounding an end of the cavity, and a back mirror bounding an opposite end of the cavity. The back mirror has a κ_{effB} approximately equal to α_{Tune} , where κ_{effB} is an effective coupling constant and α_{Tune} is the maximum amount of propagation loss anticipated for an amount of peak tuning required, and a length of the back mirror is made to produce greater than approximately 80 % reflectivity.



For two-letter codes and other abbreviations, refer to the "Guidance Notes on Codes and Abbreviations" appearing at the beginning of each regular issue of the PCT Gazette.

IMPROVED MIRROR AND CAVITY DESIGNS FOR
SAMPLED-GRATING DISTRIBUTED BRAGG REFLECTOR LASERS

CROSS-REFERENCE TO RELATED APPLICATIONS

This application claims the benefit under 35 U.S.C. Section 119(e) of the following co-pending and commonly-assigned U.S. provisional patent application Serial No. 60/203,052, filed May 4, 2000, by Gregory A. Fish and Larry A. Coldren, entitled 5 "IMPROVED MIRROR AND CAVITY DESIGNS FOR SGDBR LASERS," attorneys' docket number 122.1-US-P1, which application is incorporated by reference herein.

BACKGROUND OF THE INVENTION

10 1. Field of the Invention.

The present invention relates generally to wide-range tunable semiconductor lasers and particularly to sampled-grating distributed Bragg reflector (SGDBR) lasers.

15 2. Description of the Related Art.

Diode lasers are being used in such applications as optical communications, sensors and computer systems. In such applications, it is very useful to employ lasers that can be easily adjusted to output frequencies across a wide wavelength range. A diode laser which can be operated at selectively variable frequencies covering a wide wavelength range is an invaluable tool. The number of separate channels that can utilize 20 a given wavelength range is exceedingly limited without such a laser. Accordingly, the number of individual communications paths that can exist simultaneously in a system employing such range-limited lasers is similarly very limited. Thus, while diode lasers have provided solutions to many problems in communications, sensors, and computer system designs, they have not fulfilled their potential based on the available bandwidth 25 afforded by light-based systems. It is important that the number of channels be increased in order for optical systems to be realized for many future applications.

For a variety of applications, it is necessary to have tunable single-frequency diode lasers which can select any of a wide range of wavelengths. Such applications include sources and local oscillators in coherent lightwave communications systems, sources for other multi-channel lightwave communication systems, and sources for use 5 in frequency modulated sensor systems. Continuous tunability is usually needed over some range of wavelengths. Continuous tuning is important for wavelength locking or stabilization with respect to some other reference, and it is desirable in certain frequency shift keying modulation schemes.

Sampled-grating distributed Bragg reflector (SGDBR) lasers obtain many of these 10 desirable features through the use of two sampled gratings bounding a gain and phase section of a semiconductor. The basic function and structure of SGDBR lasers is detailed in U.S. Patent 4,896,325, issued January 23, 1990, to Larry A. Coldren, entitled "MULTI-SECTION TUNABLE LASER WITH DIFFERING MULTI-ELEMENT MIRRORS", which patent is incorporated by reference herein. However, designing an 15 optimized SGDBR laser for a given application can be a complex, time consuming, iterative process. There is a need in the art for methods and devices that facilitate simpler, more manufacturable designing of SGDBR lasers based on application-specific performance criteria.

20

SUMMARY OF THE INVENTION

To address the issues described above, the present invention discloses a tunable laser comprised of a gain section for creating a light beam by spontaneous and stimulated emission over a bandwidth, a phase section for controlling the light beam around a center frequency of the bandwidth, a cavity for guiding and reflecting the light beam, a 25 front mirror bounding an end of the cavity, and a back mirror bounding an opposite end of the cavity. The back mirror has a κ_{eff} approximately equal to α_{Tune} , where κ_{eff} is an effective coupling constant and α_{Tune} is an amount of propagation loss anticipated for an amount of peak tuning required, and a length of the back mirror is made to produce greater than approximately 70% reflectivity (at a minimum, to approximately 80%

reflectivity at a maximum) in combination with a front mirror that is intended to produce less than approximately 25% reflectivity..

BRIEF DESCRIPTION OF THE DRAWINGS

5 Referring now to the drawings in which like reference numbers represent corresponding parts throughout:

FIGS. 1A and 1B depict a SGDBR laser showing the four sections used to control the power and wavelength of the laser's emission;

FIG. 2 is a plot of reflectivity versus wavelength of typical SGDRB laser mirrors;

10 FIG. 3 depicts composite reflectivity of the front and back mirror overlaid on the cavity modes of the laser;

FIG. 4 is a contour plot illustrating the selection of the front mirror reflectivity and length of the gain section (L_g) for minimum current and a particular output power;

15 FIG. 5 illustrates modal propagation loss in the distributed Bragg reflector (DBR) under wavelength tuning;

FIGS. 6A - 6D illustrate the maximum allowed κ for the front mirror to meet the side mode suppression ratio criteria;

FIG. 7 is a plot showing the drop in cavity reflectivity ($R_f \cdot R_b$) under tuning as a function of tuning enhancement;

20 FIG. 8 illustrates that designs with higher tuning enhancement suffer greater loss of reflectivity during tuning;

FIG. 9 shows the repeat mode limited tuning range for several front mirror peak spacings;

25 FIG. 10 is a schematic illustrating the relationship between the side mode suppression ratio of the supermode adjacent to the desired lasing wavelength;

FIG. 11 is a table of calculated examples;

FIG. 12 illustrates using two back mirror peaks for every front mirror in order to have longer gain section length without side mode suppression ratio (SMSR) problems due to adjacent cavity modes; and

FIG. 13 is a flowchart that illustrates the design process according to the preferred embodiment of the present invention

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

5 In the following description, reference is made to the accompanying drawings which form a part hereof, and which is shown, by way of illustration, an embodiment of the present invention. It is understood that other embodiments may be utilized and structural changes may be made without departing from the scope of the present invention.

10 The present invention relates to the design of widely tunable sampled-grating semiconductor lasers. More specifically, it focuses on designing the cavity and grating mirrors to achieve wider tuning range, higher output power, easier control, with less output power variations between best and worst case channels than prior art designs. See, for example, V. Jayaraman et al., "Theory, Design, and Performance of Extended

15 Tuning Range in Sampled Grating DBR Lasers," *IEEE J. Quantum Elec.*, v. 29, (no. 6), pp. 1824-1834, (June 1993), H. Ishii et al., "Quasicontinuous Wavelength Tuning in Super-Structure-Grating (SSG) DBR Lasers", *IEEE J. Quantum Elec.*, v. 32, (no. 3), pp. 433-441, (March 1996) and I. Avrutsky et al., "Design of Widely Tunable Semiconductor Lasers and the Concept of Binary Superimposed Gratings (BSG's)", *IEEE J. Quantum Elec.*, v. 34, (no. 4), pp. 729-741, (April 1998), all of which are incorporated by reference

20 herein.

FIGS. 1A and 1B show a typical SGDBR laser illustrating the four sections that allow its unique tuning characteristics. The laser 100 is comprised of a gain section 102, a phase section 104, a front mirror 108 and a back mirror 110, wherein the sections have lengths L_A , L_ϕ , L_{gF} and L_{gB} , respectively. Below these sections is a cavity 106 for guiding and reflecting the light beam, while the entire device is formed on a substrate 112. In use, generally bias voltages are connected to the top portions of the gain section 102 and a ground is connected to a lower substrate 112. When the bias voltage on the gain section 102 is above a lasing threshold, a laser output is produced from an active region 30 118.

The front and back mirrors 108, 110 are typically sampled grating mirrors that respectively include different sampling periods 114, 116. The gratings behave as wavelength-selective reflectors such that partial reflections are produced at periodic wavelength spacings of an optical signal carried in the cavity 106. The front and back 5 sampled grating mirrors together determine the wavelength with the minimum cavity loss through their effective lengths L_{eff} and L_{efm} and grating differential, however, the lasing wavelength can only occur at the longitudinal modes of the optical cavity 106. Therefore, it is important to adjust the mirrors 108, 110 and cavity 106 mode to coincide, thereby achieving the lowest cavity 106 loss possible for the desired wavelength. The 10 phase section 104 of the device shown in FIG. 1 is used to adjust the optical length L_{cav} of the cavity 106 in order to position the cavity 106 modes. Alternatively, the front and back mirrors may be formed from another modulated grating such as superstructure gratings, or other modulated gratings known to those skilled in the art.

FIG. 2 illustrates the reflectivity spectra common to many designs. The Vernier 15 relationship between the reflectivity peaks of the front and back sampled grating mirrors is what gives the SGDBR laser its enhanced tunability over a conventional DBR laser. Any wavelength within the tuning range can be reached by selecting an appropriate front and back mirror peak, and tuning them along with the phase section to achieve lasing at the desired wavelength.

20 FIG. 3 illustrates an example of the reflectivity (i.e. cavity loss) experienced by the cavity modes under this condition. Composite reflectivity, the product of the front and back mirror reflectivities are overlaid on the cavity modes of the laser. The lasing wavelength is determined by the cavity mode with the highest reflectivity. The optimum stability is achieved when the cavity mode and the mirror are in perfect alignment.

25 The nature of the Vernier sampled grating mirrors creates a complicated design space for the optimization of tuning range, output power, and mode suppression. This invention relates to a design approach and specification to achieve given performance goals with the constraints of a sampled grating mirror design. Methods are also presented to eliminate some of the constraints of the sampled grating mirrors in ways 30 that are simpler and more manufacturable than those illustrated in the prior art.

In general, the performance goals for devices intended for telecommunication applications are tuning ranges between 40 - 100 nm, fiber coupled output powers of several milliWatts up to the tens of milliWatts, and a side mode suppression ratio (SMSR) in excess of 30 dB. The tuning range of a given SGDBR design is limited by the 5 available gain-bandwidth and the "repeat mode spacing" (λ_R) which is the span in wavelength between the points of perfect alignment between the front and back Vernier sampled grating mirror reflectivity peaks (i.e. two periodic functions will coincide with a period equal to the lowest common integer multiple of their periods). A very simple approximate formula can be given by:

10

$$\lambda_R = \frac{\Delta\lambda_b \Delta\lambda_f}{\delta\lambda} \quad (1)$$

where $\Delta\lambda_b$ and $\Delta\lambda_f$ are the separation between the back and front mirror peaks, respectively, and $\delta\lambda$ is $\Delta\lambda_f - \Delta\lambda_b$.

15 One of the common questions of the design is the amount of tuning

enhancement, indicated generally by: $F < \frac{\sqrt{\Delta\lambda_b \Delta\lambda_f}}{\delta\lambda}$ that should be used to cover a given tuning range (i.e. fewer peaks with larger tuning between them, or more peaks with less peak tuning required). The present invention is intended to identify the design space that yields devices with the highest output powers, for a given tuning range and side 20 mode suppression and what tuning enhancement should be used to achieve this.

The design should focus on achieving output power, and then apply the limitation of SMSR and tuning range. Prior art designs of SGDBR lasers have made use of front and back mirrors with relatively equal reflectivity. With free range of the cavity parameters, those skilled in the art can easily apply optimization routines that result in 25 highly asymmetric cavities to produce higher output powers.

FIG. 4 illustrates an example of this kind of cavity optimization performed on a SGDBR laser. A contour plot illustrating the selection of the front mirror reflectivity

and length of the gain section (L_g) for minimum current and a particular output power. The parameters are chosen using the worst-case loss and estimated mirror penetration depths (120 - 150 μm). The back mirror has a fixed reflectivity of 0.85. A given output power can be achieved with a minimum current by adjusting the front mirror reflectivity 5 and length of the gain region for a fixed back mirror reflectivity and number of quantum wells. Indeed, experimentally the highest output power DBR lasers use anti-reflective (AR) coated facets ($R \sim 1\%$) as the front mirror with the back mirror DBR reflectivity (without loss) over 85%. To maintain SMSR in a DBR requires engineering only the cavity length and the back DBR to sufficiently suppress adjacent cavity modes. This 10 engineering involves using a fairly high grating coupling constant of between about 40 - 50 cm^{-1} , short cavity lengths and a large number of quantum wells (10). Those skilled in the art will understand that the high kappa's have been chosen to make the reflectivity of the DBR less sensitive (i.e. low penetration depth) to the large changes in optical loss that occur in the mirror during tuning.

15 FIG. 5 illustrates modal propagation loss in the DBR under wavelength tuning, inherent due to the index change required to achieve tuning. One result of this high kappa (κ) is a large DBR reflection bandwidth ($> 1 \text{ nm}$), which then requires a short gain section length ($< 400 \mu\text{m}$) to maintain a 30 dB SMSR (at 1 mW output power) over adjacent cavity modes. Providing the high output power in the presence of tuning losses 20 with a short cavity length requires the high gain per unit length (large number of quantum wells) in the active region.

Achieving these same results in SGDBR laser designs are complicated by the fact the front mirror plays a critical role in the mode suppression of the adjacent supermodes, which can be seen in FIG. 2. As the reflectivity of the front mirror is decreased, the 25 reflection bandwidth obviously broadens, thus there exists a maximum available modal index change Δn_{max} . To maintain the required sidemode suppression, the front mirror effective κ (i.e. the grating κ times the sampling duty ratio) must be decreased and a smaller tuning enhancement, F , is required (i.e. $\delta\lambda$ is inversely proportional to tuning enhancement).

FIGs. 6A - 6D illustrate the largest κ allowed for a 30 dB SMSR (at 1 mW output power) for various front mirror reflectivities (i.e. κL) as a function of the tuning enhancement used. Larger κ front mirrors (and hence shorter lengths) are allowed for designs with higher front mirror reflectivity, lower tuning enhancement and smaller 5 tuning ranges (i.e. less peak tuning).

FIG. 7 illustrates the effect of tuning on the mirror reflectivity which shows the drop in the total reflectivity ($R_f R_b$) as a function of the tuning enhancement for the mirror parameters described in FIG. 6. Larger $\delta\lambda$ with correspondingly higher κ mirrors lead to less change in the mirror reflectivity within the cavity. The smaller tuning 10 enhancements give less change in reflectivity for a given loss due to the shorter, higher κ front mirror that can be used. Additionally, the back mirrors with higher κ (45 cm^{-1} for $\kappa L=0.2$ and $\kappa L=0.3$ versus 35 cm^{-1} for $\kappa L=0.4$ and $\kappa L=0.5$) had less increase in loss due to the smaller penetration depths of these back mirrors.

While FIG. 7 shows that lower tuning enhancement designs gives less loss for a 15 given amount of tuning, they also require more tuning to achieve the same total tuning range. So the question remains: to cover a given tuning range, is it better to use more peaks with less index tuning or fewer, wider spaced peaks with more tuning? If the κ 's of the mirrors are chosen to be the maximum allowed by the SMSR criteria for a given tuning enhancement, then it is better to choose less tuning enhancement.

FIG. 8 shows that despite the larger peak tuning (and hence propagation loss in 20 the mirror) required to achieve a 45 nm tuning range for the lower tuning enhancement designs, the total drop in reflectivity is actually less because the mirrors used in the lower tuning enhancement designs are shorter and have smaller penetration depths. While this may seem counter intuitive, the DBR laser described earlier gives an example of a 25 limiting case. To achieve the highest output power when a tuning range of only 10 - 15 nm is required, one would most likely use a DBR laser (tuning enhancement of 1), where the front mirror has very small reflectivity (1%), the back mirror has a κ of $40 - 45 \text{ cm}^{-1}$. So, despite the lower tuning induced propagation loss required to achieve a given tuning

range, designs with higher tuning enhancement suffer a greater loss of reflectivity during tuning due to the longer, lower κ mirrors required to meet SMSR criteria.

The conclusions that can be drawn from FIGS. 6 - 8 are that highly asymmetric designs for SGDBR lasers to yield high output powers can be best achieved with high κ 5 mirrors ($40 - 45 \text{ cm}^{-1}$ for the back mirror) and less tuning enhancement given a minimum SMSR criteria.

To summarize the design strategy for a particular tuning range and output power, the following criteria should be met. The back mirror should be chosen to have an effective κ close to the amount of propagation loss anticipated for the amount of peak 10 tuning required ($5 - 10 \text{ nm}$, or $30 - 50 \text{ cm}^{-1}$). The maximum front mirror κ can be selected for a range of front mirror κL 's (i.e. reflectivity) using the same anticipated loss and SMSR criteria. The maximum length of the gain section can be then be determined for each front mirror κL based upon the cavity mode spacing required to suppress the adjacent cavity modes within the mirror reflection bandwidth. (See FIG. 3.) With the 15 back mirror parameters fixed, and length of the gain section limited, the various front mirror choices can be evaluated to see which yields the desired output power with the minimum current given the number of quantum wells within the design. Higher output powers of course favor lower reflectivity front mirrors, but will require increased gain to minimize the operating current. Those skilled in the can perform iterations from this 20 basic starting point to quickly arrive at a design that achieves the desired output power with the minimum current with the highest cavity losses that will be experienced under tuning and meets the minimum SMSR criteria for all channels within the tuning range.

In order to enhance the device performance even beyond what can be achieved with the design methodology previously described, requires circumventing the tradeoffs 25 that limit the performance. A fact that is consistently overlooked by the prior art is that the side modes can only exist at the modes of the cavity. Therefore, it is possible to use values of $\delta\lambda$ that are smaller than that allowed by the SMSR criteria mentioned above, if the cavity mode and mirror reflections combs are designed properly. The proper design is to choose the mirror peak and cavity mode spacing such that when a cavity mode is

positioned at the peak reflectivity, the cavity modes do not coincide with the highest reflectivity point of the adjacent peaks, thereby lowering the reflectivity experienced by the side modes. FIG. 3 illustrates an example of this. Clearly this design is easier to achieve by widening the spacing of the cavity modes. Toward this goal, the phase section 5 should be made as short as possible while still adjusting the roundtrip phase by 2π and staying below the maximum allowed current density. The gain section length can be reduced by increasing the gain per unit length of the active region (e.g. more quantum wells). Additionally, the methodology presented above will result in the shortest penetration depth (i.e. mirror length) for the SGDBR mirrors, also resulting in wider 10 cavity modes.

The following example is intended to illustrate several designs used to achieve the design goals. The main parameter that will be changed is $\delta\lambda$ which is inversely proportional to the tuning enhancement factor, F . The design goals are as follows: a tuning range of 50 nm, an output power of 6 mW and SMSR at 1 mW of 33 dB.

15 FIG. 9 shows the repeat mode limited tuning range for several front mirror peak spacings. The $\delta\lambda$'s that will be investigated are 0.4 nm, 0.5 nm, 0.6 nm and 0.7 nm. These give peak tuning requirements of 4.8 nm to 6.2 nm to achieve the desired tuning range.

20 The back mirror is desired to have as a high a reflectivity as possible with a κL of around 2.5 - 3.0 which gives a reflectivity around 80 - 85%. The effective κ should be selected based upon the tuning range required for the design. To avoid excessive loss of reflectivity under tuning, κ should roughly equal α .

25 For the cases above, the losses will be around $30 - 35 \text{ cm}^{-1}$, so a κ of 33 cm^{-1} is an optimum starting point. FIG. 5 shows the increase in passive modal waveguide loss under tuning.

The front mirror is more difficult to select, as both κ and L need to be chosen. Treat the laser as a Fabry-Perot laser with a free selection of the front mirror reflectivity and the length of the gain region. By minimizing the current required for the desired output power, one can find the reflectivity for the front mirror.

Cavity optimization equations for selecting the front mirror reflectivity are given as follows.

$$I = \left[\left(\frac{J_V + \frac{I_P \cdot \langle \alpha \rangle_{ia}}{N_w \cdot w \cdot d \cdot \ln(1/\sqrt{R_f R_b})}}{\langle g_{th} \rangle - \langle \alpha \rangle_{ia}} \right) \cdot N_w \cdot w \cdot d \cdot \ln\left(\frac{1}{\sqrt{R_f R_b}}\right) + I_P \right] \left(1 + \frac{1 + \langle \alpha \rangle_{ia} \cdot L_P}{\ln(1/\sqrt{R_f R_b})} \right)$$

5

(2)

where $I_P = \frac{q}{h\nu} \frac{P_o}{\eta_i F}$

$$R_f = R_{fo} \cdot \exp(-2 \cdot \langle \alpha \rangle_{ip} \cdot L_{pf})$$

$$10 \quad R_b = R_{bo} \cdot \exp(-2 \cdot \langle \alpha \rangle_{ip} \cdot L_{pb})$$

J_V = Volume threshold current density

N_w = Number of Quantum Wells (QWs)

w = Device width

d = QW thickness

15 $\langle \alpha \rangle_{ia}$ = Active region modal internal loss

$\langle \alpha \rangle_{ip}$ = Passive region modal internal loss

F = Fraction of power exiting front mirror

P_o = Desired output power

L_{pf} = Front mirror penetration depth

20 L_{pb} = Back mirror penetration depth

R_{fo} = Lossless front mirror reflectivity

R_{bo} = Lossless back mirror reflectivity

To apply equation (2) it is important to use the waveguide losses for the wavelength channels requiring the largest peak tuning ($30 - 35 \text{ cm}^{-1}$). This is complicated by the fact that the penetration depth of the front mirror is unknown; a guessed value is used to obtain an estimate of the desired front mirror reflectivity. The front mirror 5 reflectivity will be less than the back mirror, so its penetration depth will be about somewhere between 1 and 0.5 times that of the back mirror. Once a rough value of the desired reflectivity is determined, recalculate with a more accurate penetration depth.

For example, once it is determined that a lossless front mirror reflectivity around 0.2 - 0.25 ($\kappa L_f \sim 0.5$) is desired (as in FIG. 4), the effective κ for the front mirror is 10 selected. This is chosen based upon the SMSR criteria and the $\delta\lambda$ chosen for the design. A rule of thumb is that the half width at half maximum (HWHM) of the front mirror (including loss) should be roughly equal the $\delta\lambda/2$ (i.e. the ratio of the peak sidemode reflectivity to the desired peak reflectivity should be 0.75-0.8 for 30 dB SMSR at 1 mW and approximately 80%/20% mirrors).

15 FIG. 10 is a schematic illustrating the relationship between the SMSR of the supermode adjacent to the desired lasing wavelength and the front and back mirror reflectivity curves. FIG. 10 also uses a more rigorous equation relating the front and back mirror to properties to the SMSR. The relation is as follows.

$$20 \quad \text{SMSR} \geq \left[M + \frac{\langle \Delta g \rangle_{th}}{\langle g \rangle_{th}} \right] \cdot 10^4 \cdot (mW)^{-1} \cdot P_o(mW) \quad (3)$$

$$M_{ch} = \frac{\ln[R_b R_f(\lambda_1) / R_b R_f(\lambda_o)]}{\ln[R_b R_f(\lambda_o)]}$$

This equation can be applied to select the effective κ of the front mirror now that 25 its approximate κL is known.

FIG. 11 is a table of calculated examples. Using this design example shows that the performance of the worst channel is best for the shortest front mirror. This is a

result of the loss dominating the design space. Front mirrors with shorter penetration depths are less affected by the large losses experienced under tuning. Shortening the front mirror increases its reflection bandwidth, thereby requiring larger $\delta\lambda$ (and hence more tuning) to maintain the SMSR and tuning range requirements. It is interesting to 5 note that despite the extra tuning required, the cavity losses of the worst case channel are lower for designs with shorter mirrors. This fact is unrecognized in the prior art, which mainly addresses the increase in loss by setting $\kappa \sim \alpha$ for the mirrors. This is valid for the higher reflectivity mirrors (>0.5) used in the prior art, but the penetration depth is dominated by the length of the mirror for the low reflectivities (<0.3) needed for more 10 output power.

As higher output powers are desired, the reflectivity of the front mirror is required to be even lower (0.1 - 0.05). The larger bandwidths of these mirrors will require even larger $\delta\lambda$ (1 - 1.2 nm) with mirror lengths below 125 μm . At this point the SMSR is determined not only by the cavity modes at adjacent supermodes, but also 15 but the cavity modes within the reflection bandwidth of the main reflectivity peak. This is a result of the sum of the mirror penetration depth becoming less than 20 - 30% of the total cavity length that is required to achieve the desired filtering. Shortening the gain section length accordingly leads to excessive threshold current densities ($>4 \text{ kA/cm}^2$). A novel solution to this problem is to use twice as many back peaks as front peaks to cover 20 a given tuning range. FIG. 12 illustrates using two back mirror peaks for every front mirror in order to have longer gain section length without SMSR problems due to adjacent cavity modes. For example use twelve, 3.8 nm spaced back mirror peaks and six, 8.2 nm spaced front mirror peaks, in which the repeat mode spacing is roughly $[(\Delta\lambda_b \Delta\lambda_f) / (\Delta\lambda_f - 2 \Delta\lambda_b)]$ to cover a 50 nm range. The advantage of this arrangement is 25 that the penetration depth of the back mirror can be twice as long (thereby allowing only one cavity within its stopband for longer gain section lengths, 500 - 600 μm) and still have $\kappa \sim \alpha$, as not to suffer excessive loss under tuning (α being smaller due to the smaller peak tuning required). The narrower back mirror allows for smaller $\delta\lambda$'s to be

used given the same front mirror, making up for the fact the repeat mode spacing is two times smaller.

FIG. 13 is a flowchart that illustrates the design process 1300 according to the preferred embodiment of the present invention. Given Δn_{\max} , P_{out} , $\Delta\lambda_{\max}$, MSR as design 5 parameters, assuming HR/AR design for highly efficient output and using $\alpha_{b\max}$ from Δn_{\max} , $\kappa = \alpha_{b\max}$, the design process is detailed as follows:

- **Back Mirror:** The back mirror should be designed to specifications such that it can operate with the high losses that exist under tuning (Block 1302). To achieve this $\kappa_{\text{effB}} \sim \alpha_{\text{Tune}}$. Increase reflectivity, R_b , by increasing length until peak curvature begins to flatten. Flattening gives less adjacent mode suppression; $2 < \kappa_{\text{effB}} L_{gB} < 2.8$ and $R_b = \tanh \kappa_{\text{effB}} L_{gB}$. The length should be made to give sufficiently high reflectivity of about greater than 70% - 80% without being excessively long, so preferably $\kappa_{\text{effB}} L_{gB} \sim 2.0 - 3.0$.
- **Gain Section:** The length of the gain section is limited by the need for single mode operation (Block 1304). Use maximum total effective cavity length L_{tot} for minimum $\langle \alpha_i \rangle$ and J_{th} and R_{sp} . Max L_{tot} is determined by minimum mode spacing for desired SMSR, given the curvature and reflection level of the back mirror peak and the reflection level, R_g , of the front mirror, assume preferably ~ 0.2 . $\Delta\lambda_{\text{mode}} = \lambda^2 / (2nL_{\text{tot}})$; $L_{\text{tot}} \leq KL_{\text{effB}}$, where K is approximately about 6 and L_{effB} is and L_{effB} is the penetration depth of the rear mirror.
- **Front Mirror:** The front mirror design has the most constraints. However, it is desired to have the smallest reflectivity and shortest length that can maintain the SMSR criteria (Block 1306). To cover the desired tuning range, $\Delta\lambda_{\text{Total}}$; $\delta\lambda$, which represents the difference in mirror peak reflectivity spacing, must be chosen given the peak tuning that can be

5

achieved, as shown in FIG. 9. Once $\delta\lambda$ is chosen, the bandwidth, i.e., full width at half maximum (FWHM), of the front mirror must be chosen to give the desired SMSR. A conservative criteria is the FWHM is twice the $\delta\lambda$. To achieve 30 dB SMSR (see FIG. 10) the front mirror must roll off to around 70 - 80% of its peak value at the point of maximum back mirror reflectivity at the adjacent supermode. Clearly, higher output powers require lower reflectivity (therefore wider bandwidth) front mirrors and hence wider peak tuning is required to achieve $\Delta\lambda_{\text{total}}$, as the $\delta\lambda$ must be increased accordingly with the mirror bandwidth.

10

The magnitude of the front mirror reflectivity, R_f , is calculated from a minimization of gain current, I , for a calculated maximum total cavity length, L_{tot} and power out, P_o . The length is given by $R_f = \kappa L_{\text{gf}}$. Generall, $|R_f|$ is approximately less than about 25% for substantially reasonable powers out.

15

As provided for hereinabove, the differential supermode spacing, $\delta\lambda$, and enhancement factor, F , are calculated from the total desired tuning range, $\Delta\lambda_{\text{total}}$, and available index shift, Δn_{max} . Assume $F = \Delta\lambda_{\text{super}}/\delta\lambda$; $\Delta\lambda_{\text{super}} = \lambda\Delta n_{\text{max}}/n$; $\Delta\lambda_{\text{total}} = F\lambda\Delta n_{\text{max}}/n$. Therefore, $\delta\lambda \sim (\Delta n_{\text{max}}\lambda/n)^2/\Delta\lambda_{\text{total}}$. Since the front mirror length is twice its penetration depth for small R_f , $L_{\text{gf}} \sim \lambda^2/(2\delta\lambda n) = \Delta\lambda_{\text{total}}/2(\Delta n_{\text{max}})^2$.

20

- **Phase Section:** The phase section is required to shift the cavity modes by two mode spacings under the mirrors (Block 1308). The length should also be such that the current density is below about substantially 5 kA/cm².

25

This concludes the description of the preferred embodiment of the present invention. In summary, the present invention discloses a method making a tunable laser, comprising designing a back mirror to operate with high losses under tuning, said back

mirror bounding an end a cavity for guiding and reflecting a light beam, designing a gain section having a length limited for single mode operation, said gain section creating the light beam by spontaneous emission over a bandwidth, designing a front mirror having the smallest reflectivity and shortest length that can maintain a SMSR criteria for the 5 laser, said front mirror bounding an opposite end of the cavity and designing a phase section capable of shifting cavity modes by two mode spacings, said phase section controlling the light beam around a center frequency of the bandwidth.

The foregoing description of one or more embodiments of the invention has been presented for the purposes of illustration and description. It is not intended to be 10 exhaustive or to limit the invention to the precise form disclosed. Many modifications and variations are possible in light of the above teaching. It is intended that the scope of the invention be limited not by this detailed description, but rather by the claims appended hereto.

CLAIMS:

1. A tunable laser comprising:
 - a gain section for creating a light beam by spontaneous and stimulated emission over a bandwidth;
- 5 a phase section for controlling the light beam around a center frequency of the bandwidth;
 - a cavity for guiding and reflecting the light beam;
 - a front mirror bounding an end of the cavity; and
 - a back mirror bounding an opposite end of the cavity;
- 10 wherein the back mirror has a κ_{cmB} approximately equal to α_{Tune} , where κ_{cmB} is an effective coupling constant and α_{Tune} is an amount of propagation loss anticipated for an amount of peak tuning required, and a length of the back mirror is made to produce greater than approximately 70% reflectivity.
- 15 2 The tunable laser of claim 1, wherein a length of the gain section is chosen to minimize a composite reflectivity for all undesired cavity modes.
3. The tunable laser of claim 1, wherein the front mirror has a smallest reflectivity and a shortest length that can maintain a side mode suppression ratio criteria.
- 20 4. The tunable laser of claim 1, wherein the phase section is capable of shifting cavity modes of the laser by at least two mode spacings.
5. The tunable laser of claim 1, wherein $\kappa_{\text{cmB}} \times L_{\text{gB}}$ is approximately 2.0 to 3.0.
- 25 6. The tunable laser of claim 1, wherein a length of the gain section is no more than approximately five times a penetration depth of the back mirror.

7. The tunable laser of claim 1, wherein a length of the phase section is such that a current density of less than 5 kA/cm^2 is required to produce a cavity mode shift of two mode spacings.

5 8. The tunable laser of claim 1, wherein the front mirror has a front-back peak spacing based upon a tuning range of the laser and a bandwidth based on a side mode suppression ratio criteria.

10 9. The tunable laser of claim 1, wherein the front mirror has a bandwidth approximately two times a front-back peak spacing.

10. The tunable laser of claim 1, wherein the length of the back mirror is made to produce greater than approximately 80% reflectivity.

15 11. The tunable laser of claim 1, wherein the front mirror is intended to produce less than approximately 25% reflectivity.

12. The tunable laser of claim 1, wherein the front mirror has a length less than or substantially equal to the length of the back mirror.

20 13. A method of designing a tunable laser, comprising:
designing a back mirror to operate with high losses under tuning, said back mirror bounding an end of a cavity for guiding and reflecting a light beam;
designing a gain section having a length limited for single mode operation, said gain section creating the light beam by spontaneous and stimulated emission over a bandwidth;

25 14. A method of designing a tunable laser, comprising:
designing a front mirror having the smallest reflectivity and shortest length that can maintain a side mode suppression ratio (SMSR) criteria for the laser, said front mirror bounding an opposite end of the cavity for guiding and reflecting the light beam;

30 and

designing a phase section capable of shifting cavity modes by two mode spacings, said phase section controlling the light beam around a center frequency of the bandwidth.

5 14. The method of claim 13, wherein the back mirror has a κ_{effB} approximately equal to α_{Tune} , where κ_{effB} is an effective coupling constant and α_{Tune} is an amount of propagation loss anticipated for an amount of peak tuning required.

10 15. The method of claim 13, wherein a length of the back mirror is made to produce greater than approximately 80% reflectivity.

16. The method of claim 13, wherein $\kappa_{\text{effB}} \times L_{\text{gs}}$ is approximately 2.5 to 3.0.

17. The method of claim 13, wherein the length of the gain section is chosen 15 to limit the number of cavity modes within a stop band of the back mirror.

18. The method of claim 13, wherein the length of the gain section is no more than approximately five times the penetration depth of the back mirror.

20 19. The method of claim 13, wherein the phase section is designed having a length such that a current density equal to or less than 5 kA/cm^2 shifts the cavity modes by two mode spacings.

25 20. The method of claim 13, wherein the front mirror has a front-back reflection peak spacing based upon a tuning range of the laser and a bandwidth based on a side mode suppression ratio criteria.

21. The method of claim 13, wherein the front mirror has a bandwidth approximately two times a front-back peak spacing.

22. The method of claim 13, wherein the front mirror is formed to have a reflectivity of less than or equal to 25%.

23. A tunable laser, comprising:
5 a back mirror capable of operating with high losses under tuning, said back mirror bounding an end of a cavity for guiding and reflecting a light beam;
a gain section having a length limited for single mode operation, said gain section creating the light beam by spontaneous stimulated emission over a bandwidth;
a front mirror having the smallest reflectivity and shortest length that can
10 maintain a side mode suppression ratio (SMSR) criteria for the laser, said front mirror bounding an opposite end of the cavity; and
a phase section capable of shifting cavity modes by two mode spacings, said phase section controlling the light beam around a center frequency of the bandwidth.

15 24. The tunable laser of claim 23, wherein the back mirror has a κ_{emb} approximately equal to α_{Tune} , where κ_{emb} is an effective coupling constant and α_{Tune} is a maximum of an amount of propagation loss anticipated for an amount of peak tuning required.

20 25. The tunable laser of claim 23, wherein a length of the back mirror is made to produce greater than approximately 80% reflectivity.

26. The tunable laser of claim 23, wherein $\kappa_{\text{emb}} \times L_{\text{gb}}$ is approximately 2.5 to 3.0.

25 27. The tunable laser of claim 23, wherein the length of the gain section is chosen to suppress cavity modes within a stop band of the back mirror.

28. The tunable laser of claim 23, wherein a cavity length of the gain section
30 is no more than approximately five times a penetration depth of the back mirror.

29. The tunable laser of claim 23, wherein the phase section has a length such that its current density is below 5 kA/cm² for necessary adjustment of the cavity mode wavelength.

5

30. The tunable laser of claim 23, wherein the front mirror has a front-back mirror reflecting peak spacing based upon a tuning range of the laser and a bandwidth based on a side mode suppression ratio criteria.

10 31. The tunable laser of claim 23, wherein the front mirror has a bandwidth approximately two times a front-back mirror reflectivity peak spacing.

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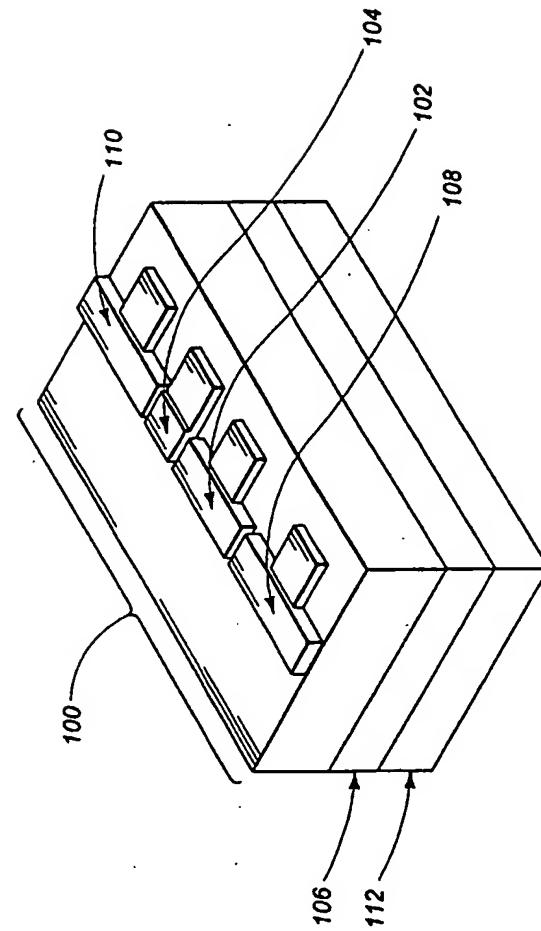


FIG. 1A

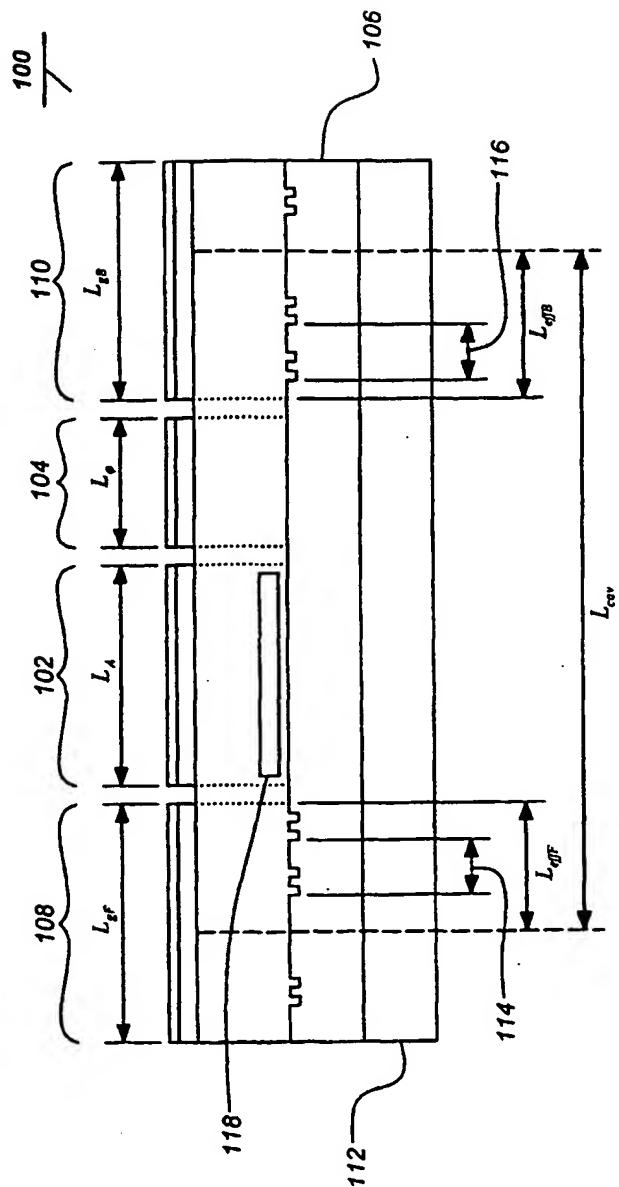


FIG. 1B

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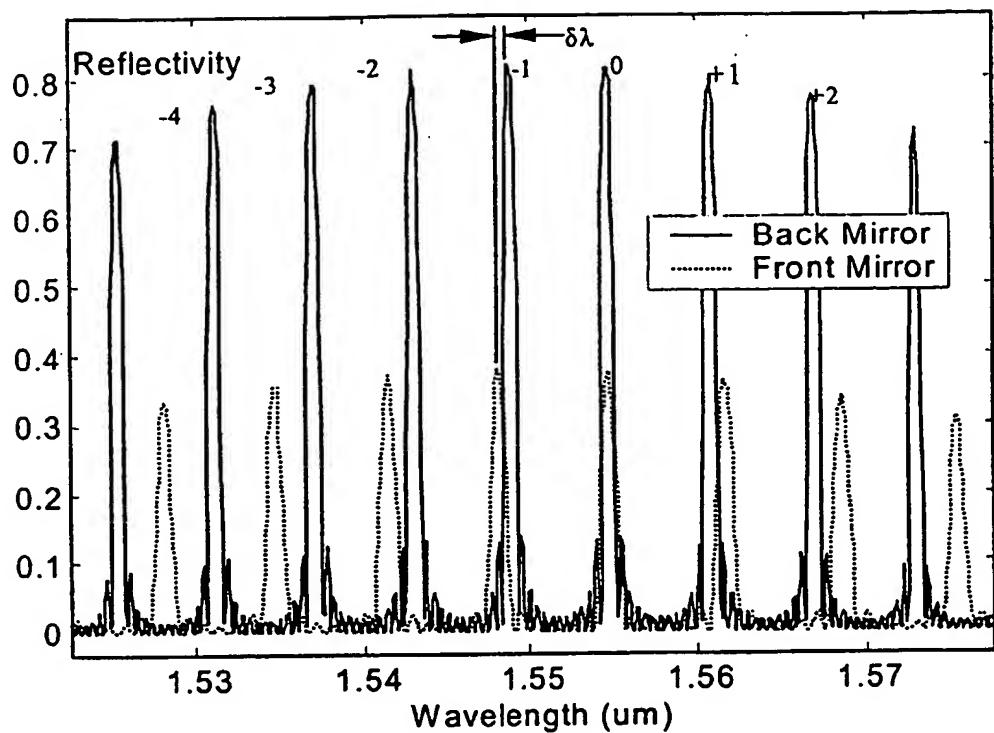


FIG. 2

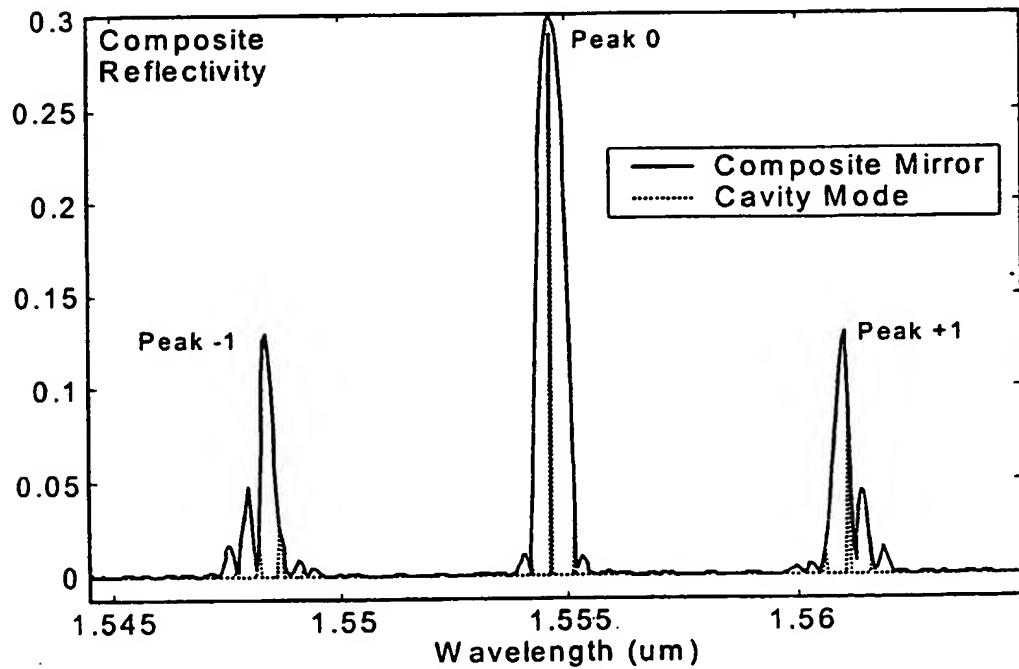


FIG. 3

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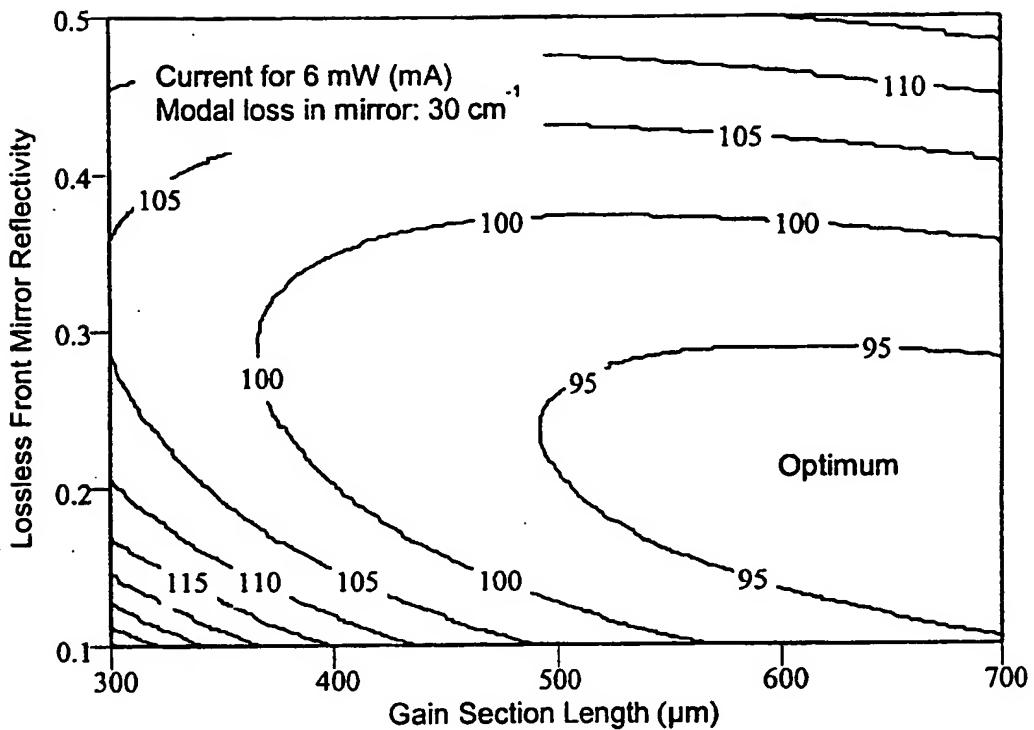


FIG. 4

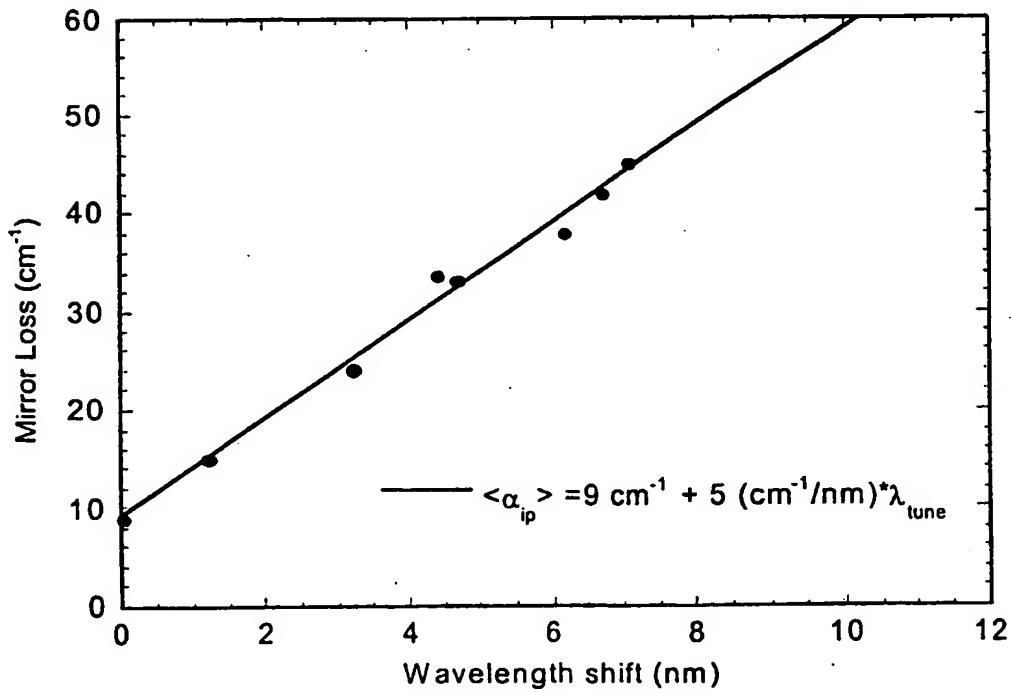


FIG. 5

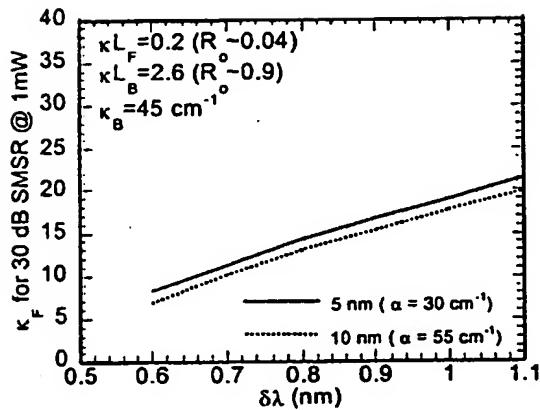


FIG. 6A

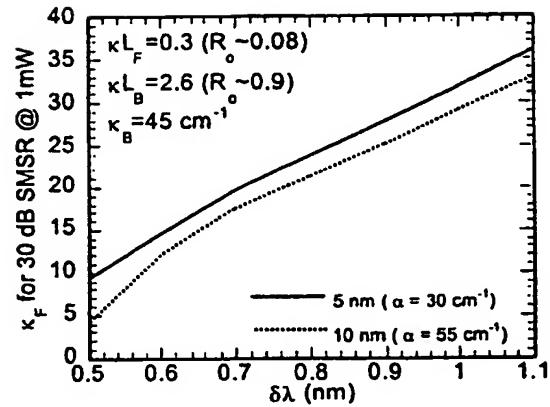


FIG. 6B

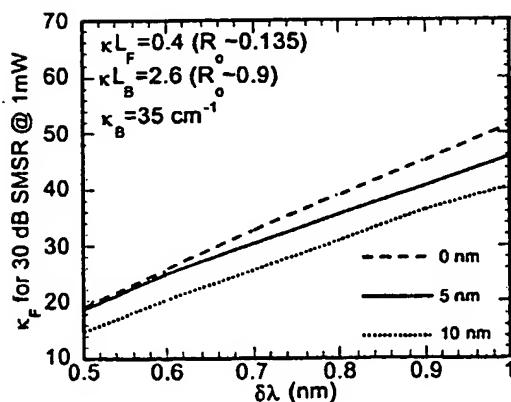


FIG. 6C

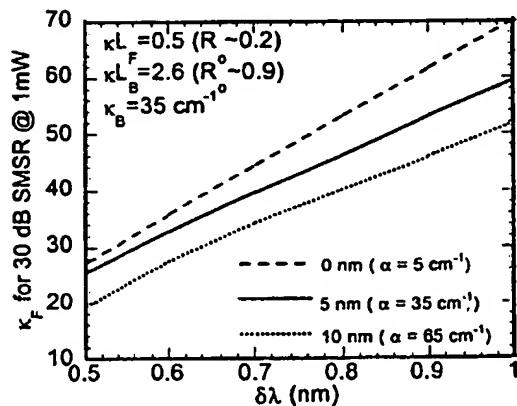


FIG. 6D

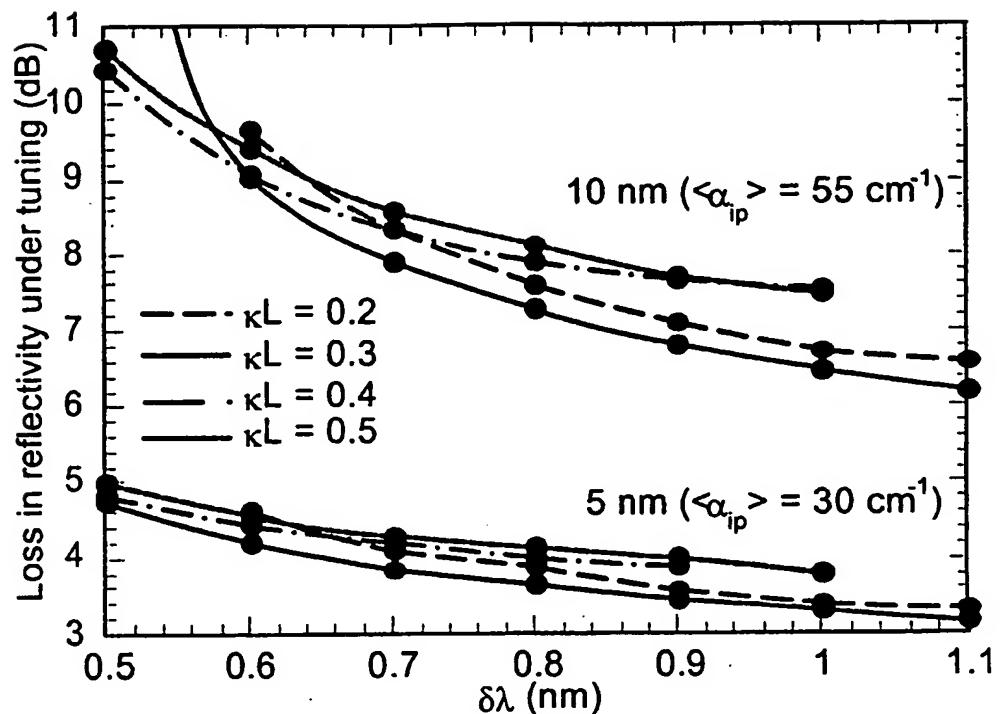


FIG. 7

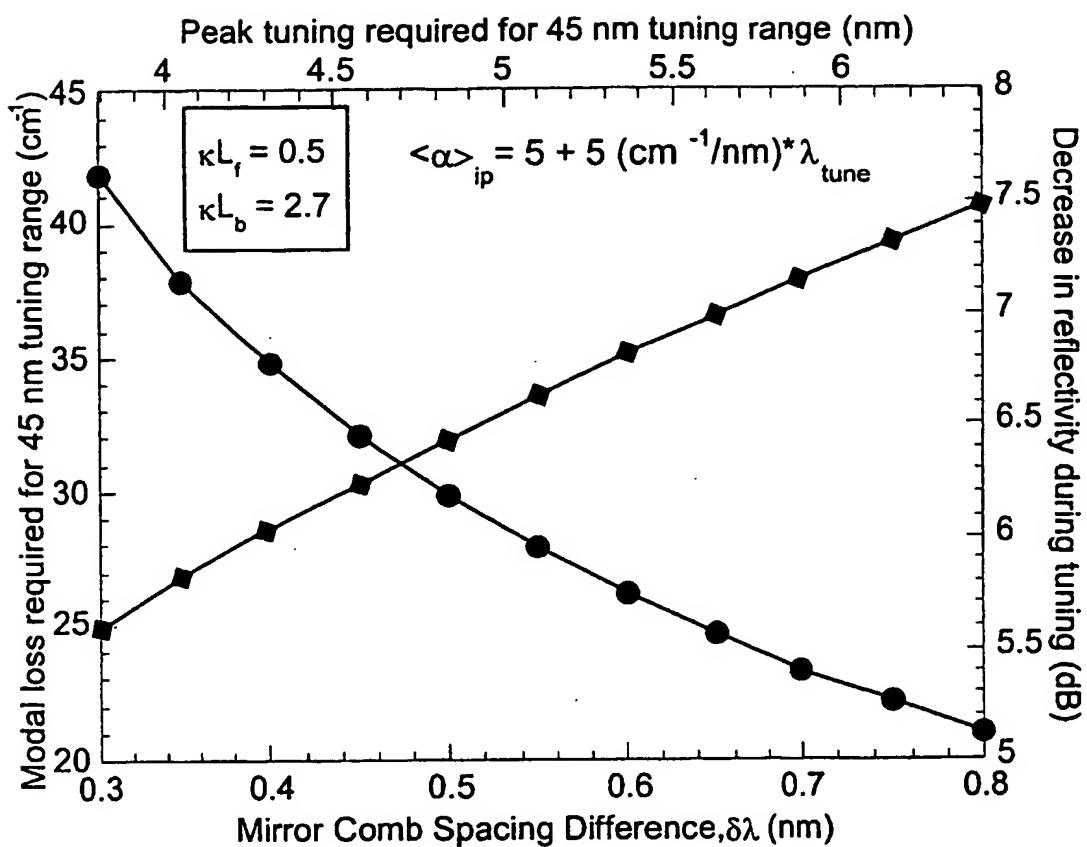


FIG. 8

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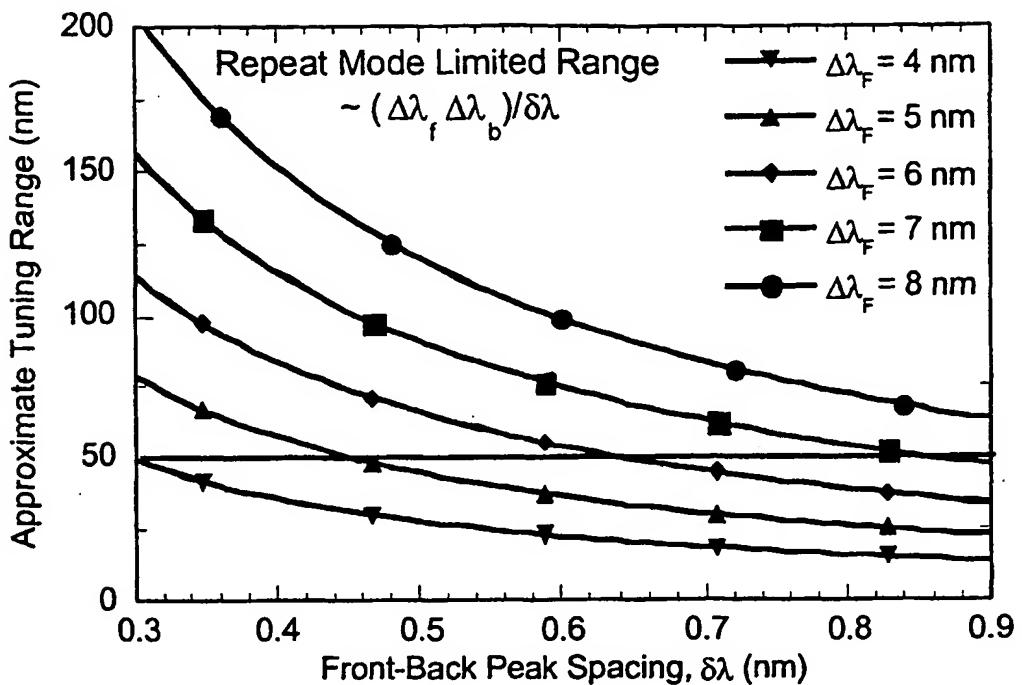


FIG. 9

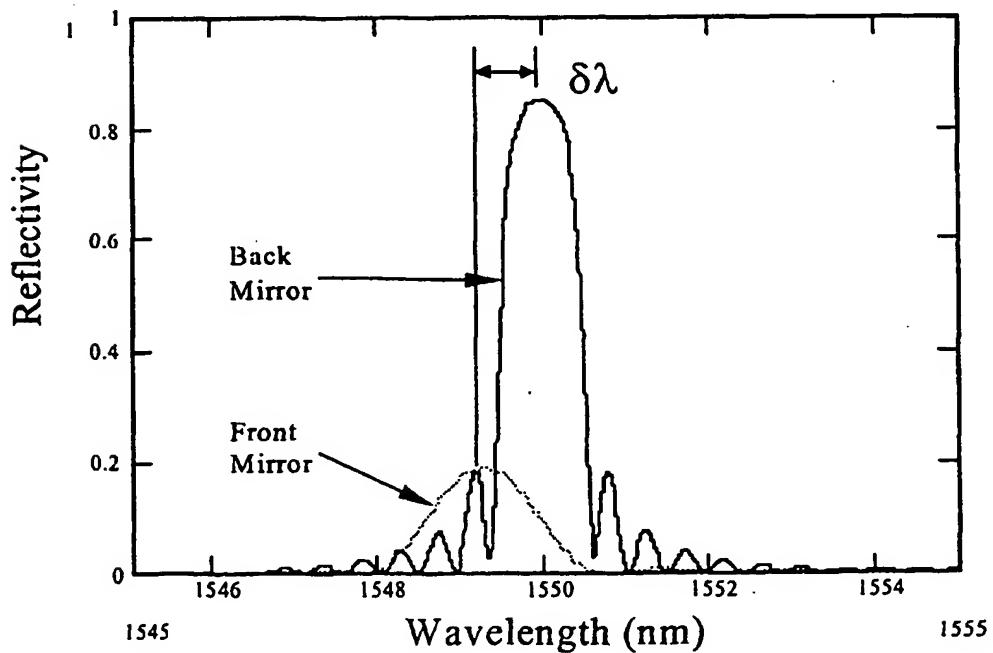


FIG. 10

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Parameter	$\delta\lambda$ 0.4 nm	$\delta\lambda$ 0.5 nm	$\delta\lambda$ 0.5 nm	$\delta\lambda$ 0.6 nm	$\delta\lambda$ 0.7 nm
P_o	6 mW				
SMSR @ 1mW	33 dB	33 dB	30 dB	33 dB	33 dB
Injection Efficiency	0.75	0.75	0.75	0.75	0.75
Tuning Range	50 nm				
Peak Tuning Required ($\Delta\lambda_f + \delta\lambda/2$)	4.8 nm	5.5 nm	5.5 nm	5.9 nm	6.5 nm
Current for P_o max	103 mA	103 mA	81 mA	93 mA	79 mA
Current for P_o min	47 mA	46 mA	43 mA	45 mA	44 mA
Gain Section Length	550 μm	550 μm	500 μm	550 μm	550 μm
Threshold current density min	1.4 kA/cm ²	1.3 kA/cm ²	1.3 kA/cm ²	1.3 kA/cm ²	1.3 kA/cm ²
Threshold current density max	2.6 kA/cm ²	2.6 kA/cm ²	2.5 kA/cm ²	2.4 kA/cm ²	2.3 kA/cm ²
Grating κ	350 cm ⁻¹				
Front Mirror R (lossless)	0.216	0.232	0.258	0.245	0.206
Front Mirror κ (cm ⁻¹)	12 cm ⁻¹	14.4 cm ⁻¹	23.1 cm ⁻¹	19.2 cm ⁻¹	24.0 cm ⁻¹
Front Mirror Period	68.7 μm	60.6 μm	60.6 μm	56.4 μm	51.0 μm
Front Mirror Burst	2.4 μm	2.5 μm	4 μm	3.1 μm	3.5 μm
Front Mirror Burst Number	6	6	4	5	4
Front Mirror Length (μm)	346 μm	305 μm	185 μm	229 μm	156 μm
Back Mirror Reflectivity	0.812	0.84	0.85	0.85	0.85
Back Mirror κ	26.5 cm ⁻¹	31.3 cm ⁻¹	32.4 cm ⁻¹	33.2 cm ⁻¹	36.5 cm ⁻¹
Back Mirror Period	75.3 μm	67.0 μm	67.0 μm	63.2 μm	57.5 μm
Back Mirror Burst	5.7 μm	6 μm	6.2 μm	6 μm	6 μm
Back Mirror Burst Number	13	13	13	13	12
Back Mirror Length	909 μm	810 μm	810 μm	764 μm	638 μm

FIG. 11

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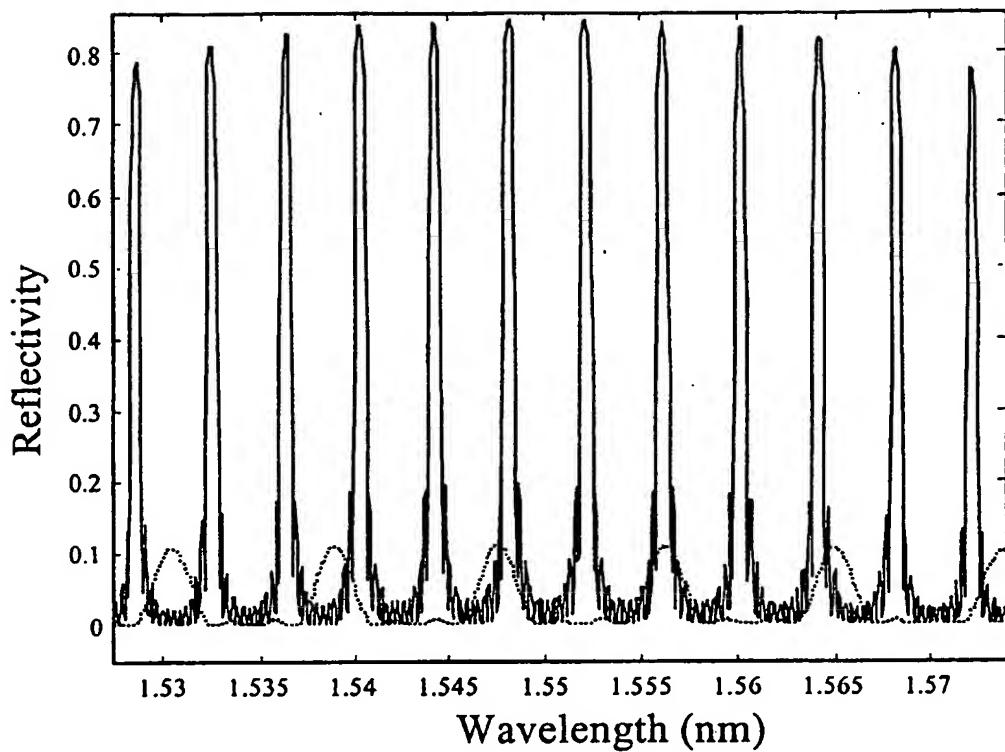


FIG. 12

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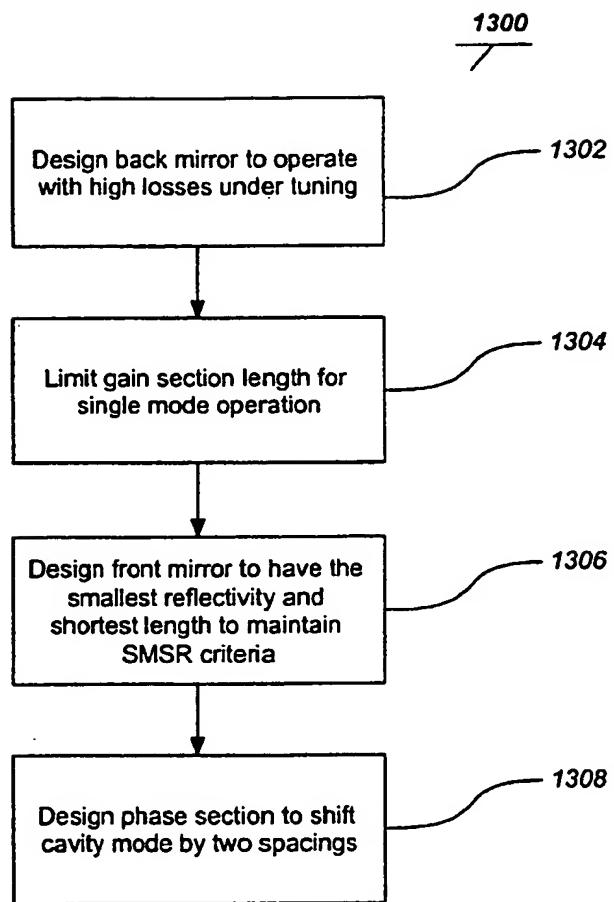


FIG. 13